

			ND USER):					
Company: Address:			Contact:		Tit	Title:		
			Phone:		Fa			
Country:			Email:					
Other Contact Info:								
2. FIXTURE B	UILDER / I	LINE INTI	EGRATOR:					
Company:			Contact:		Tit	tle:		
Address:			Phone:	Fax:				
Country:			Email:					
Other Contact Info:			-					
3. APPLICATION Number of different								
Description of part(s		naica:						
Drawings of part(s)		omer:	Yes	☐ No	Drawing	format:		
Part(s) Available for	Runoff / Tryout	:: Yes	☐ No Pict	ure/ Video of t	he work area?	☐ Yes	□No	
Picture/ Video of the	part being hand	lled today? [Yes No					
If different, are parts	run in batch or	random sequen	ce: Batch	Rand	om			
Dimensions of part:		T						
Description:	Weight:	Height:	Width:	Length:	I.D.	O.D.		
							Please attach list of	
							additional	
							sizes if	
							applicable	
Surface Finish:	Wet Oily	Dry D	Hot °F	°C	Class A	Fragile Tex	ctured Other	
If other explain:								
_								
Description of Curre	ent Process / Seq	uence of Opera	ntion:					
								
								
Production Rate:	Jobs per hour:		_					
What is the justificat	-	•			_			
Reduce Manpow	er 🗌 Ergon	omics	Safety		New Product	☐ Ne	w Work Cell	



4. PART PICK UP:		FIRST P	ICK UP:	S	ECOND PICK	UP:	
* What is the part being picked to	ap from:						
Are there obstructions around pa	Yes		No [Yes	☐ No		
* If yes, specify:							
* Suggested area for attaching de	evice to part:						
* Areas of the part that should no	ot be touched:						
* Part Orientation at pick up (op	erator's perspective):						
* Part elevation at pick up (dime	ension):						
Provide necessary sketches whe	re * appears						
5. PART SET DOWN:		FIRST SI	ET DOWN:	SI	ECOND SET D	OWN:	
* What is the part being set down	n into / onto:	-					
Are there obstructions around pa	art at set down:	Yes Yes		No [Yes	☐ No	
* If yes, specify:							
* Part Orientation at set down (o							
* Part elevation at set down (dimension):							
Provide necessary sketches whe							
6. HANDLING DEVICE FEATURES:							
Style of Handling Device:	□ Duoleo □ II.	- a1-	□ т	C) Oth on			
Clamp Vacuum Probe Hook Trap Other Type of Controls: Single Set or Dual Set Controls:							
Type of Controls: ☐ ZA ☐ EA ☐ 2PS ☐ BA ☐ Ele							
ZA EA 2P	S BA E	lectronic		Single		Dual	
* Motion of Handling Device:							
Straight Transfer If not, indicate the desired motion	on shown below:						
A O							
	1		/		.4/		
			Y	+	Y	7	
	Z			>		2	
ROTATE						TU T	
			SWIVEL			TILT	
Operators	Rotate Degrees:			Degrees:	☐ Tilt □	Degrees:	
perspective	_ :	 Ianual	☐ Power	Manual	Power	Manual	
* Specify rotation and / or tilt as viewed by the operator:							
Provide necessary sketches when	re * appears.						



/. ENVIRONME	NI:						
Air Pressure:	☐ 60-70 PSI	☐ 70-80 PSI	☐ 80-90 P	SI [Other PSI		
Electrical Supply:	☐ 115 VAC		If other, please specif	Y			
Operating Conditions: Conditions that require customer mfg. Specifications:							
Hot	Cold Corrosive	Dusty	Clean Room	Food / Bev	verage		
° F	° F						
° C	° C						
Elevation from floor to bottom of header steel or Enclosed Rail:							
Type of Rail:							
8. MOUNTING C	PTIONS:						
Balancer Style:	TIONS.						
150 lb (68 Kg)	200 lb. (90 Kg)	350 lb. (158 Kg)	500 lb. (227 Kg)	Intelift:	Other:		
Arm Style: ☐ 400	□ 600 □ 70	0	701	713	□ 720		
	REQUIREMENTS: required? (extra charge)	□ No □	Yes If yes, indicate to	he desired CAD	format		
Type of review if red		On Site	•	Special	None		
	•			•	_		
10. SPECIAL REC	QUIREMENTS OR CUS	TOMER SPECIF	ICATIONS:				
Prepared by:				Date:			



